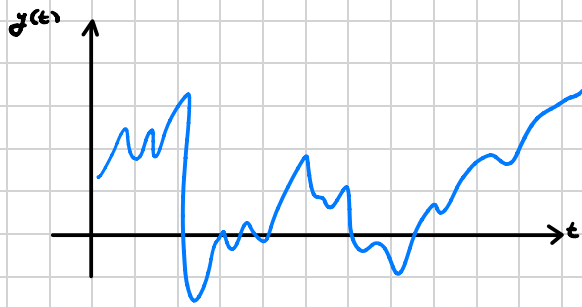


24103 - Nonparametric Identification

In Time series domain have worked with stationary stochastic processes. Looking only 1 realization you cannot infer the other. We would like, starting from a portion of a single realization of SSP, we may want to infer some of its statistical properties



mean (m_y) covariance ($\gamma_y(\tau)$) spectrum ($\Gamma_y(\omega)$)

So far we have followed these steps to find them: Collect measurement, create a data set, identify the model $W(z)$, and compute the desired measure $m_y = E[y(t)] = W(z)E[e(t)]$. This is a **model based approach** (not direct).

Sample based estimation

Sample Mean: we want to find a direct estimation of the expected value m_y of $y(t)$

$$D_N = \{y(1), \dots, y(N)\} \rightarrow m_y = E[y(t)]$$

The most natural estimator is the **mean over time**.

$$\hat{m}_N = \frac{1}{N} \sum_{t=1}^N y(t)$$

Is this a 'good' estimator for the real m_y ? We need to define what 'good' means:

DEF Property of correctness: an estimator is **correct** if the expected value of the estimator is equal to the probabilistic property to be estimated

For the mean $E[\hat{m}_N] = m_y$. Is $\hat{m}_N$ correct? Yes!

$$E[\hat{m}_N] = E\left[\frac{1}{N} \sum y(t)\right] = \frac{1}{N} \sum E[y(t)] = \frac{1}{N} \sum m_y = \frac{N}{N} m_y = m_y$$

Is correctness enough?

DEF: Consistency: an estimator is **consistent** if the variance of the estimation error tends to zero, as the number of data tends to ∞

For the mean: $E[(\hat{m}_N - m_y)^2] \rightarrow 0$ for $N \rightarrow \infty$. Is $\hat{m}_N$ consistent? For example, consider $y(t,s) = v(s) \quad \forall t$ with $v(s) \sim N(0,1)$

$$\begin{aligned} E[(\hat{m}_N - m_y)^2] &= E\left[\left(\frac{1}{N} \sum y(t,s) - m_y\right)^2\right] = E\left[\left(\frac{1}{N} \sum v(s)\right)^2\right] \\ &= E\left[\frac{1}{N} \sum v(s)^2\right] = E[v^2(s)] = 1 \quad \forall N \end{aligned}$$

The variance is constant to 1 for any N (more sample does not add any information). So this is not consistent!

Theorem: if $\gamma(\tau) \rightarrow 0$ as $|\tau| \rightarrow \infty$, then $\hat{m}_N$ is consistent

The condition $\gamma(\tau) \rightarrow 0$ for $|\tau| \rightarrow \infty$ is true for all ARMA/ARMAX processes (for the ARMAX one, the exogenous part is always deterministic and fully known).

Covariance Function: we want to find a direct estimation

$$D_N = \{y(1), \dots, y(N)\} \rightarrow \gamma_y(\tau) = E[y(t)y(t-\tau)] \quad \forall \tau$$

For simplicity we assume $m_y = 0$ without loss of generality. One possible estimator is

$$\hat{\gamma}_N(\tau) = \frac{1}{N-\tau} \sum_{t=1}^{N-\tau} y(t)y(t+\tau) \quad (\text{or } \hat{\gamma}_N(\tau) = \frac{1}{N} \sum_{t=1}^N y(t)y(t-\tau))$$

Notice that:

- we cannot use any τ : $0 \leq \tau \leq N-1$ (Theoretically true, but we cannot compute close to these bounds)
- $\hat{\gamma}_N(0) = [y^2(1) + \dots + y^2(N)] / N$ average over N elements
- $\hat{\gamma}_N(1) = [y(1)y(2) + \dots + y(N-1)y(N)] / (N-1)$ average over $N-1$ elements
- $\hat{\gamma}_N(N-1) = [y(1)y(t+\tau=N)] \cdot 1$ average computed over one single pair of samples
- From a practical point of view, we can compute in a reliable way only for $\tau \ll N-1$

What about negative τ ? We recall that $\delta_Y(\tau) = \delta_Y(-\tau)$, so we consider $|\tau|$ instead of simply τ ; so we can write

$$\hat{\delta}_N(\tau) = \frac{1}{N-|\tau|} \sum_{t=1}^{N-|\tau|} y(t)y(t+|\tau|)$$

Is $\hat{\delta}_N(\tau)$ correct? By applying the formula:

$$E[\hat{\delta}_N(\tau)] = E\left[\frac{1}{N-|\tau|} \sum y(t)y(t+|\tau|)\right] = \frac{1}{N-|\tau|} \sum E[y(t)y(t+|\tau|)] = \frac{1}{N-|\tau|} \delta_Y(\tau) = \delta_Y(\tau) \quad \checkmark$$

Is $\hat{\delta}_N(\tau)$ consistent? We have to introduce a new theorem

Theorem: $\hat{\delta}_N(\tau)$ is consistent if $\delta(\tau) \rightarrow 0$ for $\tau \rightarrow +\infty$

Spectral Density: we want to find a direct estimation

$$D_N = \{y(1), \dots, y(N)\} \Rightarrow \Gamma_Y(\omega) = \sum_{\tau=-\infty}^{+\infty} \delta(\tau) e^{-j\omega\tau} \quad \forall \omega$$

One possible estimator is

$$\hat{\Gamma}_N(\omega) = \sum_{\tau=-(N-1)}^{N-1} \hat{\delta}_N(\tau) e^{-j\omega\tau}$$

we have a problem due to the **approximation**:

- sum boundaries: $(N-1)$ and $-(N-1)$
- $\hat{\delta}_N(\tau)$ from previous approximation

This is again an indirect non parametric estimator as we need to estimate $\hat{\delta}_N(\tau)$ first

Is $\hat{\Gamma}_N(\omega)$ correct?

$$\begin{aligned} E[\hat{\Gamma}_N(\omega)] &= E\left[\sum \hat{\delta}_N(\tau) e^{-j\omega\tau}\right] \\ &= \sum E[\hat{\delta}_N(\tau)] e^{-j\omega\tau} \quad \text{is correct so this coincide with } \delta_Y(\tau) \\ &= \sum_{\tau=-(N-1)}^{N-1} \delta_Y(\tau) e^{-j\omega\tau} \neq \Gamma_Y(\omega) \end{aligned}$$

This is not correct (since $-(N-1) \neq -\infty$ and $N-1 \neq +\infty$) but it is asymptotically correct, so

$$\lim_{N \rightarrow +\infty} E[\hat{\Gamma}_N(\omega)] = \Gamma_Y(\omega) \quad \forall \omega$$

Is $\hat{\Gamma}_N(\omega)$ consistent? $E[(\hat{\Gamma}_N(\omega) - \Gamma_Y(\omega))^2] \rightarrow \Gamma_Y(\omega)$ for $N \rightarrow +\infty$

The error is large with large quantity

$$\text{Moreover: } E[(\hat{\Gamma}_N(\omega_1) - \Gamma_Y(\omega_1))(\hat{\Gamma}_N(\omega_2) - \Gamma_Y(\omega_2))] \rightarrow 0$$

no correlation between errors at ω_1 and ω_2 .

There are several way to deal with that. One is **AVERAGING** (or "regularization"):

Take the dataset and divide it into fixed portion and compute the estimation of only one portion

If N is large also $\frac{N}{5}$ is good to be used for estimation

The average will compensate the fluctuation of each predictor

So:

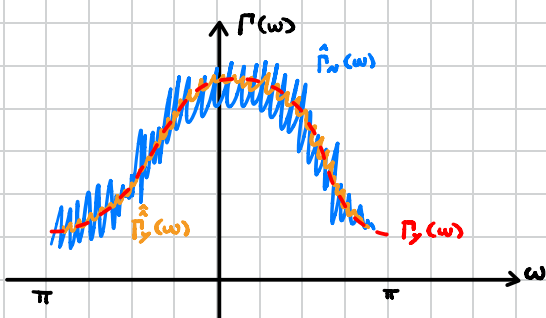
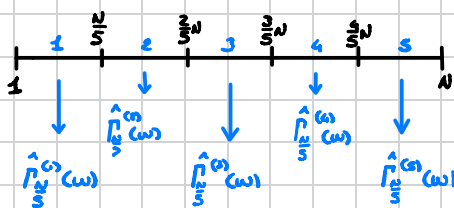
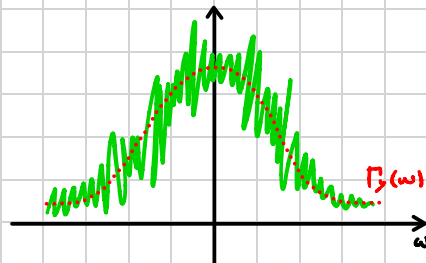
$$\hat{\hat{\Gamma}}_N(\omega) = \frac{1}{5} \sum_{i=1}^5 \hat{\Gamma}_{\frac{N}{5}}^{(i)}(\omega)$$

We could prove that $\frac{N}{5}$ is "large" then

$$E[(\hat{\hat{\Gamma}}_N(\omega) - \Gamma_Y(\omega))^2] \approx E[(\hat{\Gamma}_N(\omega) - \Gamma_Y(\omega))^2] \frac{1}{5}$$

we are introducing a really small bias (can be ignored) with N very large

The number of parts cannot be too large, otherwise the estimate would be biased (bias/variance tradeoff not convenient anymore!)



The sampled spectrum is typically computationally more demanding than the other sample estimators. Let's take a different estimator of $\hat{S}_y(\omega)$

$$\hat{S}_N(\omega) = \frac{1}{N} \sum_{\ell=1}^{N-1} y(\ell) y(\ell + \tau)$$

This is only asymptotically correct

It can be proven that $\hat{\Gamma}_N(\omega) = \sum \hat{S}_N(\omega) e^{-j\omega\tau}$ is equivalent to $\hat{\Gamma}_N(\omega) = \frac{1}{N} \left| \sum_{\ell=1}^N y(\ell) e^{-j\omega\ell} \right|^2$

So you can see that $\hat{\Gamma}_N$ can be computed directly from $y(\ell)$ and this is the Discrete Fourier Transformation DFT of $y(\ell)$ (we can compute this easily with a lot of tools)